

Zeyad M. Manaa

Academic Belt Road, King Fahd University for Petroleum and Minerals, Dhahran, 31261, Saudi Arabia
(+966) 566-707-476, [LinkedIn](#), [GitHub](#), [Scholar](#)
<https://zmanaa.github.io/>

- EDUCATION**
- Eindhoven University of Technology** *May, 2025 – Present; Eindhoven, NL*
PhD. in Mechanical Engineering, Dynamics and Control Group
- King Fahd University for Petroleum & Minerals (KFUPM)** *2022 – 2024; Dhahran, SA*
M.Sc. in Aerospace Engineering
Thesis¹: “Data-driven Approaches for Modeling and Control in Flight Dynamics Applications – On Linear and Nonlinear Methods”
- University of Science and Technology at Zewail City (UST-ZC)** *2017 - 2022; Giza, EG*
B.S. in Aerospace Engineering
Thesis: “Development of the software package for the attitude determination and control algorithm of a cube satellite”
- INTERESTS**
- Data-driven modeling and control of dynamical systems and system identification – Non-linear and optimal control theory for flight dynamics – Event-triggered control – Secure control
- REFEREED PUBLICATIONS**
- Journal Papers**
- [1] **Novel Airfoil for Improved Supersonic Performance with Convex Optimization Approach**
Zeyad M. Manaa, Naef A. A. Qassem
The International Journal of Numerical Methods for Heat and Fluid Flow, 2024
- Conference Proceedings**
- [2] **Data-driven Discovery of The Quadrotor Equations of Motion Via Sparse Identification of Nonlinear Dynamics**
Zeyad M. Manaa, Mohamed R. Elbalshy, Ayman M. Abdallah
AIAA SCITECH 2024 Forum, AIAA (p. 1308)
- [3] **Koopman-LQR Controller for Quadrotor UAVs from Data**
Zeyad M. Manaa, Ayman M. Abdallah, Mohamed A. Abido, Syed S. A. Ali
IEEE SM 2024
- [4] **Optimum Configuration for Hovering N-Quadrotors Carrying a Slung Payload**
Mohssen M., Pansy Elkhodary, Meral Badr, Mohammed Sayegh, **Zeyad M. Manaa**, Ayman M. Abdallah
AIAA SCITECH 2025 Forum
- [5] **Design and Analysis of the Effect of Trimmable Vertical Stabilizers for Enhanced Aircraft Maneuverability and Directional Stability**
Shaik Zaidan, Najwa Z. B. Taufik, Eman Mahmoud, **Zeyad M. Manaa**, Ayman M. Abdallah, Ghulam Abro, Mohd Taib
IEEE Conference on Systems, Process, and Control (ICSPC) 2024
- PREPRINTS**
- [6] **KOETC: Koopman Operator-Based Event-Triggered Control from Data**
Zeyad M. Manaa, Ayman M. Abdallah, Mohamed Ismail, Sami El-Ferik
European Journal of Control. Under review.
- [7] **Evaluation of Deep Learning-based Quadrotor UAV Detection and Tracking Methods**
Mohssen E. Elshaar*, **Zeyad M. Manaa***, Mohammed R. Elbalshy*, Abdul Jabbar Siddiqui, abd Ayman M. Abdallah
Submitted to Engineering Applications of Artificial Intelligence

¹This work is conducted with the Interdisciplinary Research Center for Aviation & Space Exploration under research grant INAE 2401. For outcomes see e.g., [2, 3, 6].

PATENTS	[8] Efficient Airfoil for Improved Supersonic Performance for Fighters Naef A. A. Qassem, Zeyad M. Manaa <i>Patent ID. 550544US. Status: filed</i>
RESEARCH EXPERIENCE	<p>KFUPM, Space and Aviation Electronics Lab <i>Jan 2023 – Present; Dhahran, Saudi Arabia</i> <i>Research Assistant</i></p> <ul style="list-style-type: none"> • Researching Koopman operator to globally linearize nonlinear dynamics • Exploring novel techniques for adaptive and model predictive control using new data-driven techniques • Developing data-driven event-triggered control frameworks <p>NUST, Aerial Robotics Lab <i>Jun 2022 – Aug 2022; Islamabad, Pakistan</i> <i>Research Intern</i></p> <ul style="list-style-type: none"> • Developed an autonomous control system for a quadrotor UAV using Tello and COEX Clover devices with ROS <p>Egyptian Space Agency, ADCS Lab <i>Aug 2021 – Jul 2022; Cairo, Egypt</i> <i>Research Intern</i></p> <ul style="list-style-type: none"> • Conducted the bachelor's thesis research under co-supervision of the Egyptian Space Agency and University of Science and Technology at Zewail City on spacecraft attitude determination and control subsystem • Developed the software of the attitude determination and control algorithm of a cube satellite which decreased the detumbling time of the cube satellite • Studied and implemented the space environment as a means of Earth's Magnetic Field (IGRF Model), Earth's gravitational field (using Spherical Harmonics) as well as modeling the space disturbances
INTERNSHIPS	<p>EgyptAir Maintenance and Engineering <i>Jun. 2022 – Aug. 2022; Cairo, Egypt</i> <i>Maintenance Engineering Intern [hands-off]</i></p> <p>Cairo University <i>Aug. 2021 – Jul. 2022; Cairo, Egypt</i> <i>Undergraduate Visiting Student – Space Systems Technology Laboratory</i></p>
TEACHING	<p>Courses Taught</p> <p>[1] AE 426; Fall 2023: Introduction to Flight Mechanics (Undergraduate Course)</p> <p>[2] AE 315; Fall 2023: Systems and Control (Undergraduate Lab); overall evaluation: 9.56/10.0</p> <p>Teaching Assistantships</p> <p>[3] AE 540; Spring 2024, Spring 2025: Flight Dynamics and Control I (Graduate Course)</p> <p>Teaching-related Activities</p> <p>[4] AE 350 – CIE 350; Summer 2023: Monitored undergraduate students' cooperative work in Aerospace Engineering and Control & Instrumentation Engineering Departments</p> <p>[5] AE 399 – CIE 399; Summer 2023: Oversaw undergraduate students' summer internships workflow in Aerospace Engineering and Control & Instrumentation Engineering Departments</p>
TALKS	<p>Koopman Meets LQR for Quadcopters using Data <i>Sep. 2024; Ontario, Canada</i> Host: IEEE @ OntarioTech.</p> <p>Data-driven Modeling and Control in Aerospace Applications <i>Mar. 2024; Dhahran, KSA</i> Host: KIKX @ KFUPM. (Approximately 50 attendees).</p> <p>Data-driven Discovery of Quadrotors Equations of Motion Via SINDy <i>Jan. 2024; FL, USA</i> Host: AIAA</p> <p>On POD and DMD for aerodynamics application <i>May 2023; Dhahran, KSA</i> Host: Aerospace Department, KFUPM.</p>

Convex optimization for thin airfoil design using linear flow theory Mar. 2023;
Dhahran, KSA
Host: Aerospace Department, KFUPM.

AWARDS **Mohammad Al-Aqeel Grant for Graduate Students** KFUPM, 2023
Graduate Intl. Research Assistance Scholarship KFUPM, 2023
Research Intern Scholarship for Intl. Students NUST, 2022
Future Work is Digital Scholarship Ministry of Comm. and Info. Tech., 2022
Smart City Hackathon: 1st Place Award in global finals DAN & Global Project Partners,
2019
Undergraduate Fellowship UST-ZC, 2017

SKILLS **Programming:** Python (*Advanced*), MATLAB (*Advanced*), C++ (*Intermediate*), Julia (*Basic*)
Hardware: Quanser 3DOF hover system, CUAV autopilots, Raspberry Pi, Pixhawk
Frameworks: Pytorch, OpenCV, Sci-Kit, cvx/cvxpy, ArduPilot (Multi-copter), ROS
Other skills: GIT, SolidWorks, ANSYS, Mathematica, bash-scripting, \LaTeX
Languages: Arabic (Native), English (C1, IELTS: 7 [*test date: Dec, 2021*])

SERVICES **Reviewer:**
Conferences: IEEE SMILE 2024, IEEE eSmarTA, 2024, AIAA SCITECH, 2023 – 2024
Journals: European Journal of Control, 2025.

LEADERSHIP **Media Committee Head, Euroavia Zewail City** Egypt, 2020
EXPERIENCE Managed a team of 10 people for the Euroavia Egypt student branch
Media Committee Head, Zewail City Science Festival Egypt, 2019
Managed a team of 15 people for the Zewail City Science Festival mega event